Shortcuts to Adiabaticity, Optimal Quantum Control, and Thermodynamics Telluride, July 2014

Transitionless quantum driving in open quantum systems

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OUTLINE

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Berry's transitionless quantum driving

$$\hat{H}_0(t)|\varphi_n(t)\rangle = E_n(t)|\varphi_n(t)\rangle$$

if the initial state of the system is an instantaneous eigenstate of a time dependent Hamiltonian Ho it will remain the the corresponding eigenstate at time t as long as Ho varies slowly enough and there are no level crossing

$$\hat{H}(t) = \hat{H}_0(t) + \hat{H}_1(t) \qquad \hat{H}(t) |\varphi_n(t)\rangle = i\partial_t |\varphi_n(t)\rangle$$

transitionless quantum driving: add a new time dependent hamiltonian term H1 so that the state becomes an exact solution regardless of the speed of change of the hamiltonian

a classical analog



the rotating frame

$$\hat{H}(t) = \sum_{i,j} |i\rangle \langle i|\hat{H}(t)|j\rangle \langle j$$
$$\hat{U}(t) = \sum_{i} |\varphi_i(t)\rangle \langle i|$$

U(t) diagonalizes the hamiltonian

$$\hat{U}^{-1}(t)\hat{H}(t)\hat{U}(t) \equiv \hat{H}_{d}(t) = \sum_{i} E_{i}(t)|i\rangle\langle i|$$

the time dependent Schoedinger eq.

 $|\psi\rangle_{\rm d} = \hat{U}^{-1} |\psi\rangle$. time dependent unitary transformation

 $\hat{H}_{d}(t) + i\partial_{t}\hat{U}^{-1}(t)\hat{U}(t)]|\psi\rangle_{d} = i\partial_{t}|\psi\rangle_{d}$

$$[\hat{H}_{\mathrm{d}}(t) + \hat{H}_{\mathrm{d}}'(t) + \hat{H}_{\mathrm{nd}}'(t)]|\psi\rangle_{\mathrm{d}} = i\partial_t |\psi\rangle_{\mathrm{d}}.$$

$$\hat{H}_{\rm d}'(t) = i \sum_{i \neq j} |i\rangle \langle i|\partial_t \hat{U}^{-1}(t) \hat{U}(t)|i\rangle \langle i| = i \sum_{i \neq j} \langle \dot{\varphi}_i |\varphi_i\rangle |i\rangle \langle i|,$$
$$\hat{H}_{\rm nd}'(t) = i \sum_{i \neq j} |i\rangle \langle i|\partial_t \hat{U}^{-1}(t) \hat{U}(t)|j\rangle \langle j| = i \sum_{i \neq j} \langle \dot{\varphi}_i |\varphi_j\rangle |i\rangle \langle j|,$$

transitionless quantum driving

Berry connection

$$\hat{H}_{\rm d}'(t) = i \sum |i\rangle \langle i|\partial_t \hat{U}^{-1}(t) \hat{U}(t)|i\rangle \langle i| = i \sum \langle \dot{\varphi}_i |\varphi_i\rangle |i\rangle \langle i|,$$

non adiabatic term

$$\hat{H}'_{\mathrm{nd}}(t) = i \sum_{i \neq j} |i\rangle \langle i|\partial_t \hat{U}^{-1}(t) \hat{U}(t)|j\rangle \langle j| = i \sum_{i \neq j} \langle \dot{\varphi}_i |\varphi_j\rangle |i\rangle \langle j|,$$

transitional quantum driving

$$\hat{H}_{tqd}(t) = -\hat{U}(t)\hat{H}'_{nd}(t)\hat{U}^{-1}(t).$$

adiabatic approximation in open quantum systems

$$\mathcal{L}[\varrho] = -i[\hat{H}(t), \varrho] + \frac{1}{2} \sum_{j=1}^{N} (2\hat{\Gamma}_j(t)\varrho\hat{\Gamma}_j^{\dagger}(t) - \{\varrho, \hat{\Gamma}_j^{\dagger}(t)\hat{\Gamma}_j(t)\})$$

due to the coupling of the system with the environment, the energy-difference between neighbouring eigenvalues of the Hamiltonian no longer provides the natural time-scale with respect to which a time-dependent Hamiltonian could be considered to be slowlyvarying.

adiabaticity of open systems is reached when the evolution of the state of a system occurs without mixing the various Jordan blocks into which L can be decomposed.

a matrix reppresentation of ${\cal L}$

define a time independent basis in the D2-dimensional space of the density matrices. This could consist, for example, the three Pauli matrices and the identity matrix in the case of a single spin-1/2.

$$B \equiv \{\hat{\sigma}_i\} \qquad i = \{1, \dots, D^2\}.$$

the density operator becomes a vector

$$|\varrho\rangle\rangle = (\rho_1, \rho_2, \dots, \rho_{D^2})^{\dagger},$$

the Lindblad operator becomes a super matrix $L(t)|\varrho\rangle\rangle = |\dot{\varrho}\rangle\rangle$.

$$\rho_j = \operatorname{Tr}[\hat{\sigma}_j^{\dagger} \varrho] \qquad \qquad L_{jk}(t) = \operatorname{Tr}[\hat{\sigma}_j^{\dagger}(\mathcal{L}_t[\hat{\sigma}_k])].$$

Jordan decomposition

Although the supermatrix L(t) might be non-Hermitian, in which case it cannot be diagonalized in general, it is always possible to find a similarity transformation C(t) such that L(t) is written in the canonical Jordan form

$$L_{\rm J}(t) = C^{-1}(t)L(t)C(t) = {\rm diag}[J_1(t), \dots, J_N(t)],$$

$$C(t) = \sum_{\nu=1}^{N} \sum_{\mu_{\nu}=1}^{M_{\nu}} |\mathcal{D}_{\nu,\mu_{\nu}}(t)\rangle\rangle\langle\langle\sigma_{\nu,\mu_{\nu}}|,$$

$$L(t)|\mathcal{D}_{\nu,\mu_{\nu}}(t)\rangle\rangle = |\mathcal{D}_{\nu,\mu_{\nu}-1}(t)\rangle\rangle + \lambda_{\nu}(t)|\mathcal{D}_{\nu,\mu_{\nu}}(t)\rangle\rangle,$$

 $|\mathcal{D}_{\nu,0}(t)\rangle
angle$ represents the eigenvector of L(t) $\lambda_{\nu}(t)$ corresponding to the the eigenvalue

transitionless open dynamics

formal analogy with the unitary case $(L_{\rm J} + L'_{\rm J} + L'_{\rm nd})|\varrho\rangle\rangle_{\rm J} = |\dot{\varrho}\rangle\rangle_{\rm J},$

$$L'_{\rm J} = \sum |\sigma_{\nu,\mu_{\nu}}\rangle\rangle\langle\langle\sigma_{\nu,\mu_{\nu}}|\dot{C}^{-1}C|\sigma_{\nu,\mu_{\nu}}\rangle\rangle\langle\langle\sigma_{\nu,\mu_{\nu}}|$$
$$L'_{\rm nd} = \sum_{\nu\neq\nu'} |\sigma_{\nu,\mu_{\nu}}\rangle\rangle\langle\langle\sigma_{\nu,\mu_{\nu}}|\dot{C}^{-1}C|\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu,\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu,\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma_{\nu',\mu'_{\nu'}}\rangle\langle\langle\sigma$$

transitionless quantum driving

$$L_{\rm tqd} = -CL'_{\rm nd}C^{-1}$$

the driving term can be unitary (hamiltonian) or non unitary (a quantum channel)

are
$$\left\langle \left\langle \dot{\mathcal{D}}_{i}(t) \middle| \mathcal{D}_{j}(t) \right\rangle \right\rangle = \frac{\left\langle \left\langle \mathcal{D}_{i}(t) \middle| \dot{L}(t) \middle| \mathcal{D}_{j}(t) \right\rangle \right\rangle}{\lambda_{j} - \lambda_{i}}$$

for one dimensional Jordan blocks the off diagonal matrix term of the correction term are rotating jump operators and unitary driving

$$\mathcal{L}[\rho] = \sum_{k} \frac{\gamma_{k}}{2} \left[2\hat{\Gamma}_{k}(t)\rho\hat{\Gamma}_{k}^{\dagger}(t) - \left\{ \hat{\Gamma}_{k}^{\dagger}(t)\hat{\Gamma}_{k}(t),\rho \right\} \right],$$
$$\hat{\Gamma}_{k}(t) = \hat{U}^{\dagger}(t)\hat{\Gamma}_{0}^{k}\hat{U}(t)$$

in the rotating frame $\tilde{\rho} = \hat{U}(t)\rho(t)\hat{U}^{\dagger}(t)$

$$\hat{\tilde{\rho}} = \sum_{k} \frac{\gamma}{2} \left[2\hat{\Gamma}_{0}^{k} \tilde{\rho} \hat{\Gamma}_{0}^{k} - \left\{ \hat{\Gamma}_{0}^{k} \hat{\Gamma}_{0}^{k}, \tilde{\rho} \right\} \right] - i \left[i\hat{\hat{U}}(t) \hat{U}^{\dagger}(t), \tilde{\varrho} \right].$$

the quantum unitary driving

$$\hat{H}_{\rm tqd}\left(t\right) = i\dot{\hat{U}}\left(t\right)\hat{U}^{\dagger}\left(t\right).$$

example 1: single spin amplitude damping

$$\mathcal{L}_{\rm ad}[\varrho] = \frac{\gamma}{2} [2\hat{\sigma}_{\boldsymbol{n}}^{-} \varrho \hat{\sigma}_{\boldsymbol{n}}^{+} - \{\hat{\sigma}_{\boldsymbol{n}}^{-} \hat{\sigma}_{\boldsymbol{n}}^{+}, \varrho\}]$$

 $\hat{\sigma}_{\boldsymbol{n}}^{-} = (\hat{\sigma}_{\boldsymbol{n}}^{+})^{\dagger} = |\downarrow\rangle_{\boldsymbol{n}} \langle\uparrow|$

amplitude damping along a time dependent direction

 $n = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)$ precession around the z axis

$$\hat{B} \equiv \left(\hat{I}, \, \hat{\sigma}_{x}, \, \hat{\sigma}_{y}, \, \hat{\sigma}_{z}\right).$$

$$\hat{H}_{tqd}(t) = (n \times \dot{n}) \cdot \hat{\boldsymbol{\sigma}},$$

 $\phi = \omega t$ $\mathcal{L}_{tqd}[\varrho] = -i \left[\hat{H}_{tqd}(t), \varrho \right]$

$$\hat{H}_{\rm tqd}\left(t\right) = i\dot{\hat{U}}\hat{\hat{U}}^{\dagger},$$

a two qubit example

$$\Gamma_{1} = \hat{U}\left(\left|0\right\rangle_{1}\left\langle1\right| \otimes \hat{I}_{2}\right)\hat{U}^{\dagger}; \quad \Gamma_{2} = \hat{U}\left(\hat{I}_{1} \otimes \left|0\right\rangle_{2}\left\langle1\right|\right)\hat{U}^{\dagger}$$

where U is a Hadamardt gate followed by a C-NOT

the liuvillian has the following fixed point: $|\psi\rangle = (1/\sqrt{2})(|00\rangle + |11\rangle)$

let's generalise by assuming U is an arbitrary single qubit rotation followed by a C-NOT. In this case the fixed point is $|\psi(t)\rangle = (\cos\theta(t)|00\rangle + \sin\theta(t)|11\rangle)$

by rotating q one can drag the fixed point

a two qubit example

by varying slowly θ one can drag the fixed point

such dragging can be achieved exactly with no constrains on speed by adding the following coherent driving:

$$H_{\rm tqd} = i\dot{\hat{U}}\hat{\hat{U}}^{\dagger} = \begin{pmatrix} 0 & 0 & 0 & -i\dot{\theta} \\ 0 & 0 & -i\dot{\theta} & 0 \\ 0 & i\dot{\theta} & 0 & 0 \\ i\dot{\theta} & 0 & 0 & 0 \end{pmatrix}$$

$$H_{\rm tqd} = -i\dot{\theta} \left(\left| 00 \right\rangle \left\langle 11 \right| + \left| 01 \right\rangle \left\langle 10 \right| \right) + {\rm h.c.}$$